

Active Taps

“Man in the Middle”

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Do You Need an Active Tap?

$$21 = \frac{1}{(A + \eta)^2 + K^2} \text{ and } =$$



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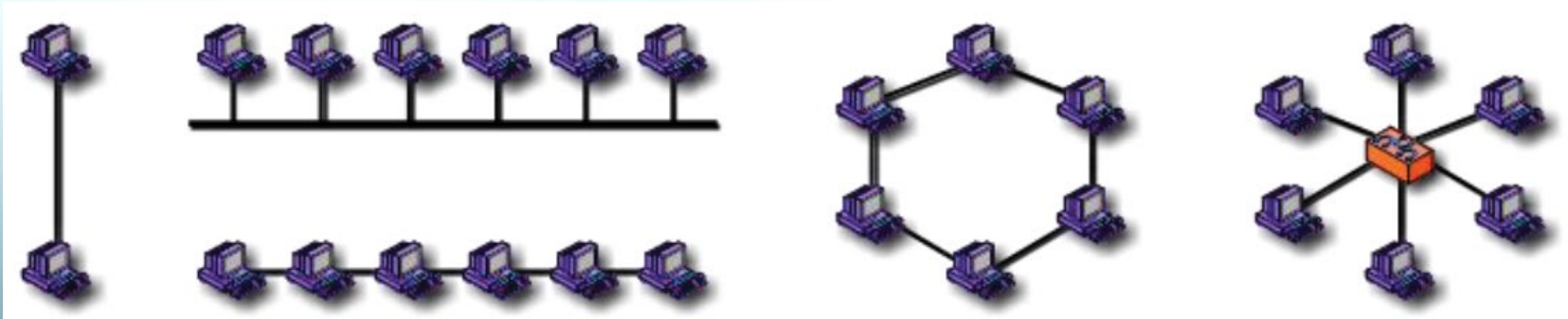
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Networking Topologies

- Point-to-point (or Port, like a "private network")
- Bus (chained or attached) (like CAN, LIN)
- Star
- Ring (very uncommon)
- Complex topologies combine these



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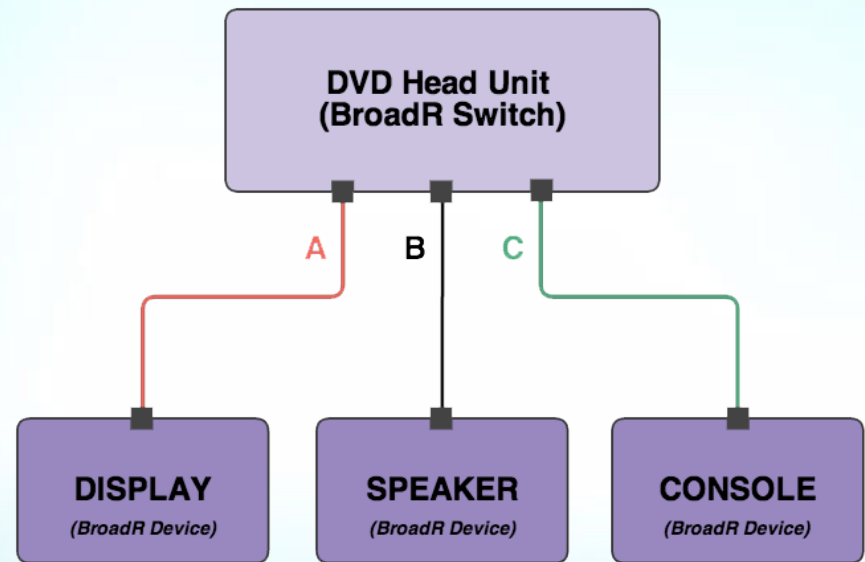
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Switched Network Architecture

- Each ECU has its own private connection to the switch (no arbitration or collision)
- Switches route data to its proper destination
- No single leg would carry all the traffic



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Wait – Where's the OBD Port??

- The topology and switched architecture means there is **no single point to get all the network data**
- The PHY is sensitive so you **cannot connect/probe it like CAN**
- Ethernet requires new tactics and new network tools for
 - Monitoring
 - Logging
 - Simulation



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How to Monitor and Simulate for AE Networks



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Monitoring / Logging AE Data

- Option 1: Use a special "debug" port on switch
 - Configure switch to send copy of all traffic on all ports to a special port
 - Plug it into your PC (if port is compatible)
- Drawbacks:
 - Added cost (if left in production)
 - Potential vulnerability
 - Bad frames not forwarded
 - Exact timing is not provided (when did it hit the wire?)
 - Adds complexity (time/resources/testing/money)
 - Bottleneck (can one port handle traffic from all the others?)



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Monitoring / Logging AE Data

- The Best Option: Use an Active Tap
 - Inserted between an ECU and its switch (or between ECUs)
 - Port Forwarding (like a gateway, with a minimal delay)
 - Port Copying (sends copies of each frame to separate Ethernet port)
 - Time/Frame Encapsulation (Includes timestamp and original frame)
- Benefits
 - Minimize cost (only insert when needed, no debug port needed)
 - Minimize vulnerability (no debug port to tempt hackers)
 - Capture even bad frames (otherwise dropped by switch / NIC)
 - Minimize complexity (debug port costs time/money/resources)
 - Minimize bottleneck



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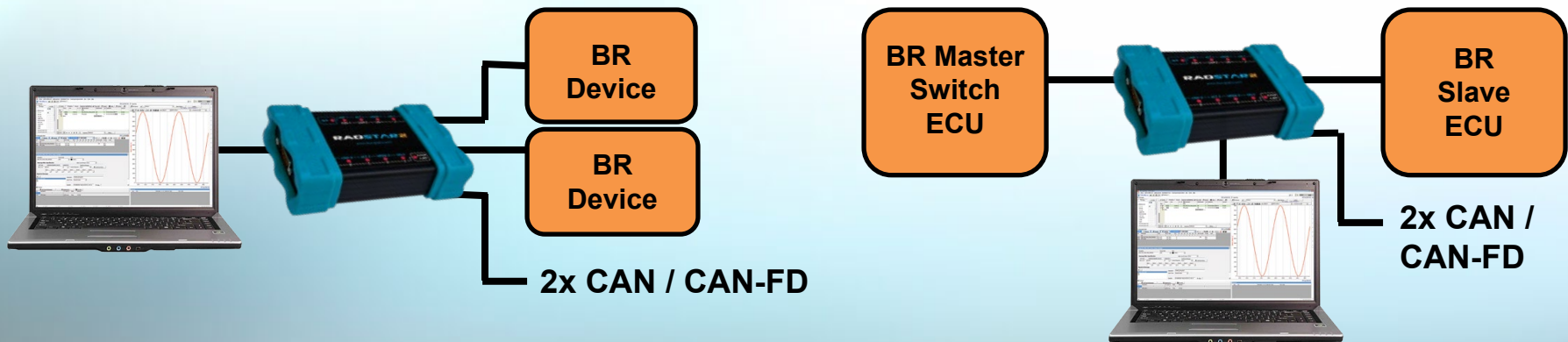
RAD-Star 2

Active-Tap for Automotive Ethernet



- Tap copies full duplex communications with sub microsecond latency
- 2x CAN / CAN-FD
- 2x BR/100BASE-T1 PHYs
- 4.5 to 36V operation

Simulate errors by introducing errors between master and slave



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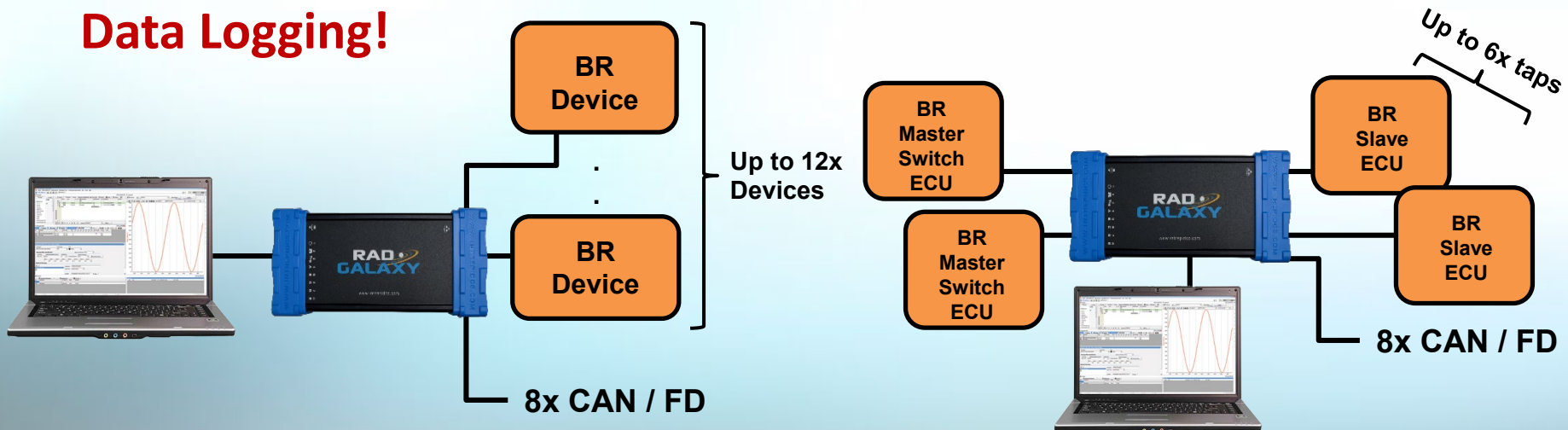


RAD-Galaxy: Multi Active-Tap



- 6x Tap copies full duplex communications with sub- μ sec latency
- 8x CAN / CAN FD
- 1x DoIP
- 12x BR /100BASE-T1 PHYs
- 4.5 to 36V operation

**Includes Standalone
Data Logging!**



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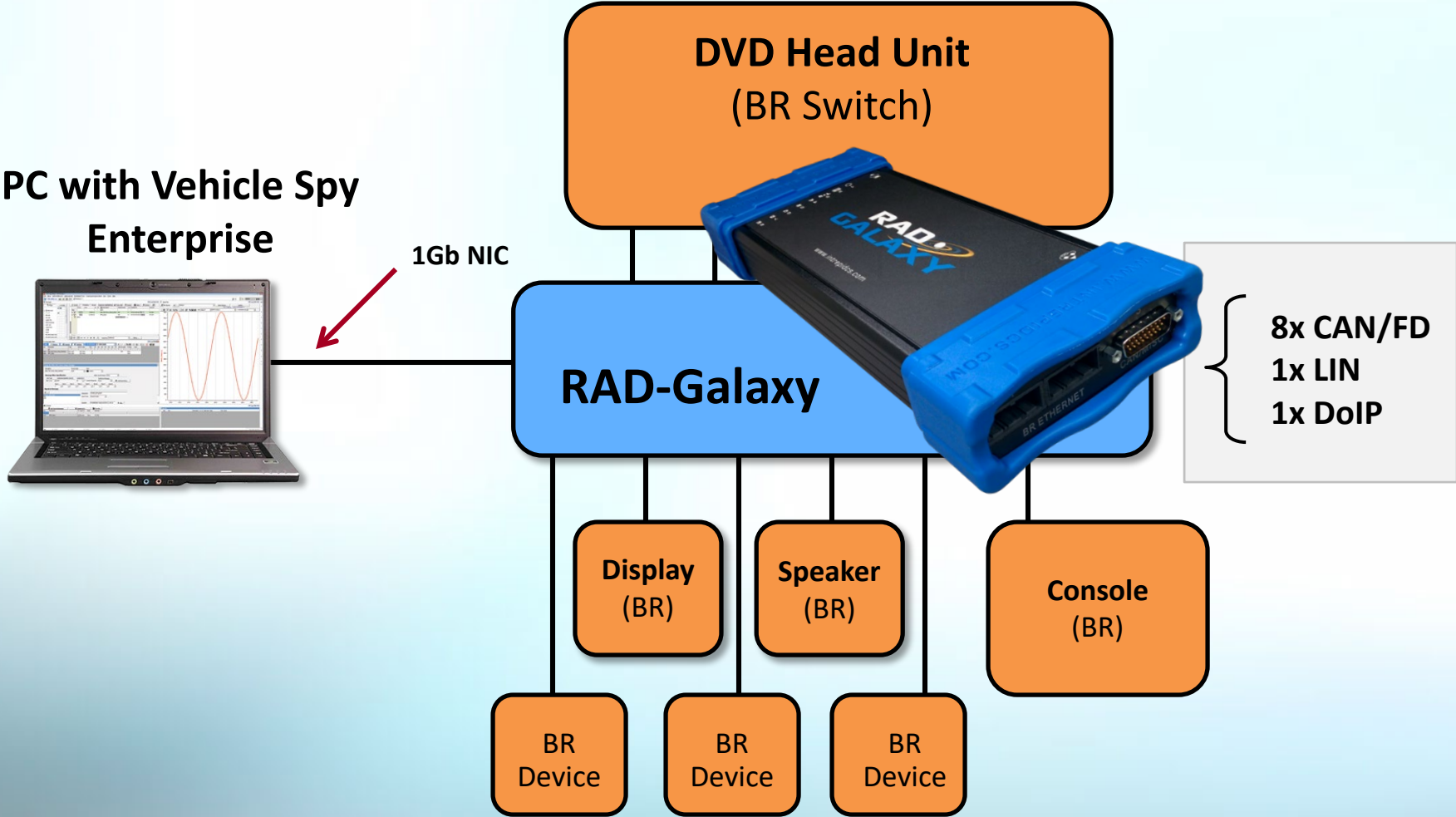
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RAD-Galaxy: Complete Solution



RAD-Gigastar

Dual Active Tap for Automotive Ethernet



- Dual Active Tap
 - 2x 100/1000BASE-T1 (Marvell)
 - 2x SFP cages for 100BASE-TX / 1000BASE-T / 1000BASE-X
- 6x CAN / CAN-FD
- 2x FlexRay (Rx Only)
- 1x SerDes (FPD Link / GMSL)
- 1x LIN/K-Line/DoIP Activation Line



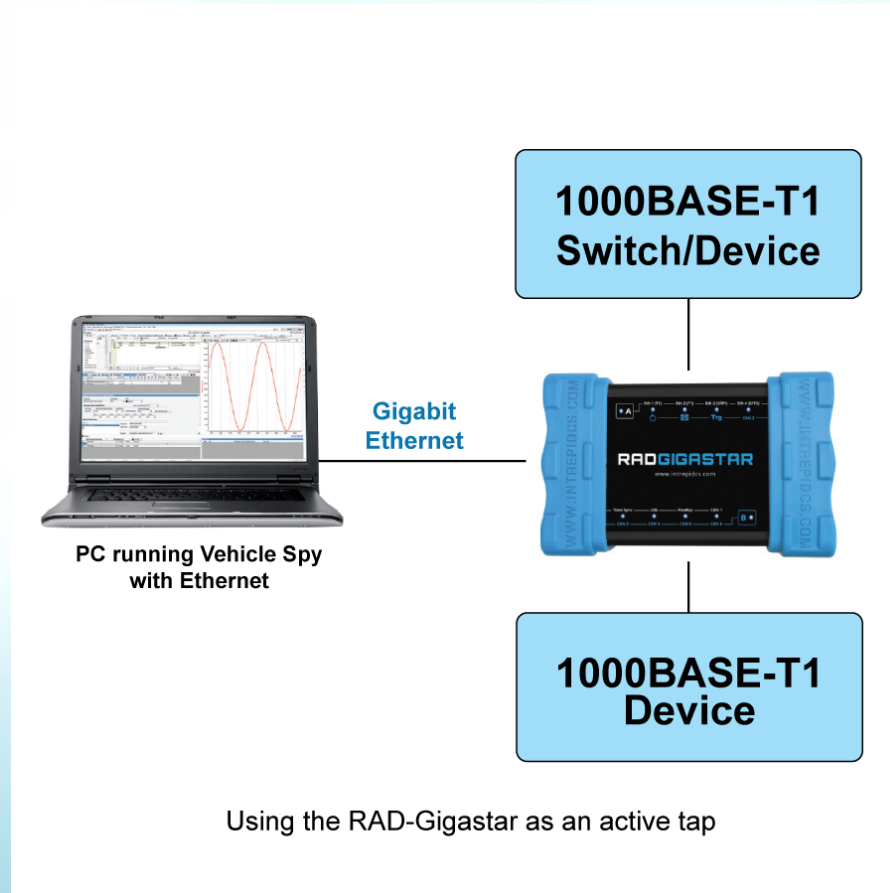
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RAD-Gigastar Use Cases



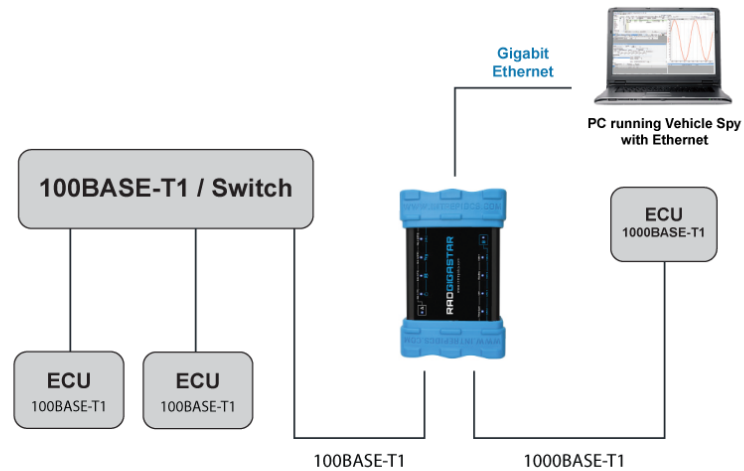
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RAD-Gigastar Use Cases



Using the RAD-Gigastar as a media converter



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Can you transmit in the middle?



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Can you transmit in the middle?

Yes!



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Ethernet and the Central Gateway Module



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Ethernet Adds Challenges

- Hacking and third-party devices via the OBD port is forcing us all to use some sort of protective gateway
- The "Central" Gateway concept includes:
 - Protection of OBD Port
 - Gateway between networks
 - Servicing OBD J1979 requests
- Ethernet adds an additional challenge



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Latency, Throughput, DoIP

- Testing of throughput will be needed
- Latency testing will be required
 - CAN-to-CAN
 - CAN-to-Ethernet
 - Ethernet-to-Ethernet
- Latency testing requires accurate timestamp from a single piece of hardware
- Testing of DoIP will also be needed eventually (Diagnostics over IP)



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