Wait -- I Only Have a 1TB Drive !!!

Welcome to the Age of Autonomous Vehicle Logging

Presented by: Jeff Warra

Log, Computer, Analyze and repeat, that's development

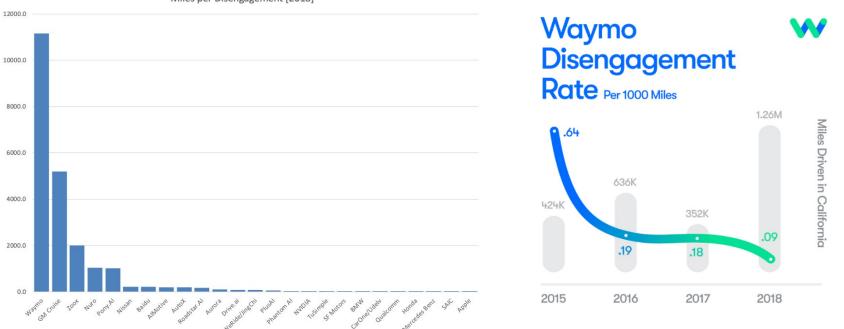


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Why do we need to log data everything ?

Miles per Disengagement [2018]



To properly reconstruct and understand disengagements

https://www.forbes.com/sites/alanohnsman/2019/02/13/waymo-tops-self-driving-car-disengagement-stats-as-gm-cruise-gains-and-tesla-is-awol/#7e559a7031ec

https://9to5mac.com/2019/02/12/apple-self-driving-disengagements/





Autonomous Sensors – Data Generators

Loads of sensors!

- Cameras
- LIDAR
- RADAR
- Automotive Ethernet
- 10GBASE-T

Gigabytes of data per second

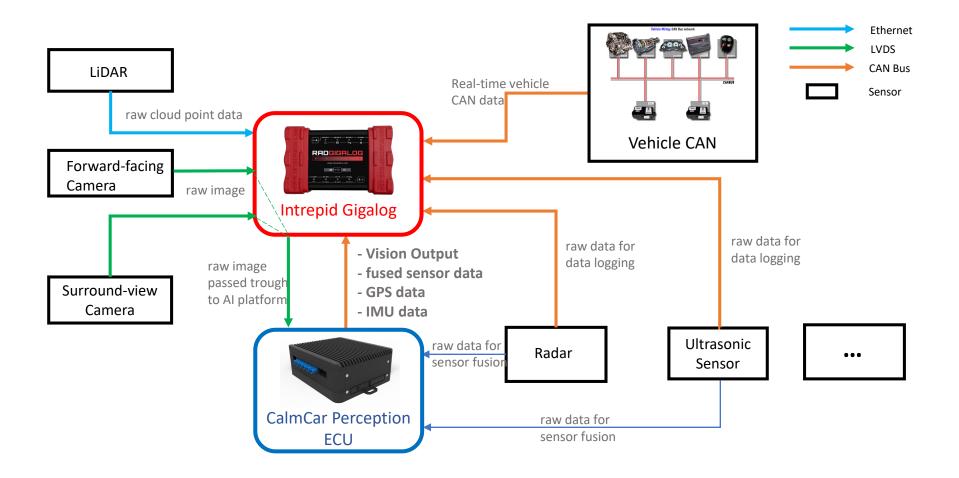








Usage Case - AI Enabled Data Acquisition Reference System





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The RAW image facts – Bandwidth

Evaluating Data pipe for RAW image transfer and Recording Times

- 2 Megapixel Camera Resolution 1920x1080 @ 30 FPS
- Pixels per second = V Res x H Res x FPS Transfer rate per image = Pixels per second x Pixels per bit (16, Camera recording format)
- Must have Bandwidth of 995 Mbps for your Camera





The RAW image facts – Adding up the Data

Evaluating Data storage size per image vs time

995 Mbps / FPS (30 FPS) = 33.2 Mbits /8= 4.1 MBytes / frame

4.1 x 30 = 123MBytes/sec * 60 = 7,380MBytes/min

7.38G * 60mins = 442.8GBytes/hr * 8 = 3.542TeraBytes/Day

1 Camera Recording in RAW format = 3.5TBytes/Day



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Logging High Bandwidth Data

Aggregated Customer Requirements

- Several gigabits of data from cameras/sensors
- Want to save everything

 Need high bandwidth logging
 Need high capacity storage
 Need high speed storage (HD, 4K, 8K)
- 6 Gbps fills 6TB in ~2 hours



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Consumer Components Unmanageable!

- Off-the-shelf CPUs and hardware are to bulky
- Requires too much power for vehicles
- Separate storage volumes







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RAD-Gigalog -<u>Log EVERYTHING</u> 6+ TB storage

- Autonomous controller logging
- Camera/Radar tapping
- CAN logging
- Long-term XCP logging
- Aurora trace logging
- Machine learning data collection





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RAD-Gigalog -<u>Log EVERYTHING</u> 6+ TB storage

Logging Interfaces

- •Ethernet Ports
 - –1x 10GBASE-T
 - -2x 100/1000BASE-T
 - -2x 100BASE-T1



- •4x SerDes High speed FPDIII/GMSL2 interface
- •8x ISO CAN FD channels
- •2x FlexRay receive-only channels



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RAD-Gigalog -<u>Log EVERYTHING</u> 6+ TB storage

Key Features

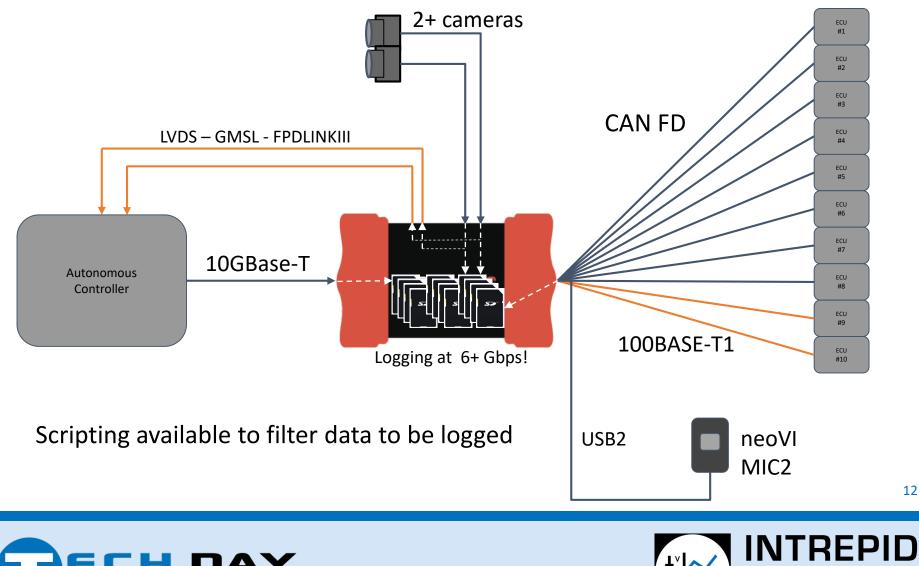
- Low power: 18W (1.5A @ 12V)
- Supercapacitor power failure protection
- USB 3 data offload/config via rugged USB-C connector
- USB 2 host for neoVI MIC2 and other accessories
- Programmable LEDs showing network and storage status
- Time sync with other Intrepid tools and autonomous logger systems (PTP)
- Integral IMU and GPS
- Optional FPGA Video Compression







High-Speed Logging



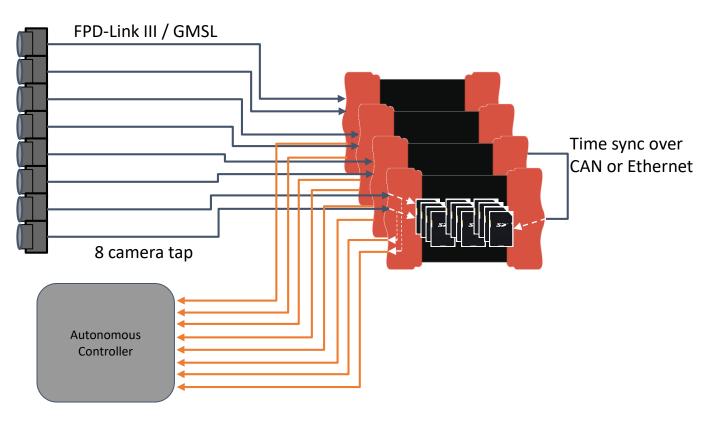
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CONTROL SYSTEMS www.intrepidcs.com

IntrepidCS

Autonomous Camera Tapping

- Log and forward uncompressed camera data
- Gang together multiple loggers for more cameras + time sync



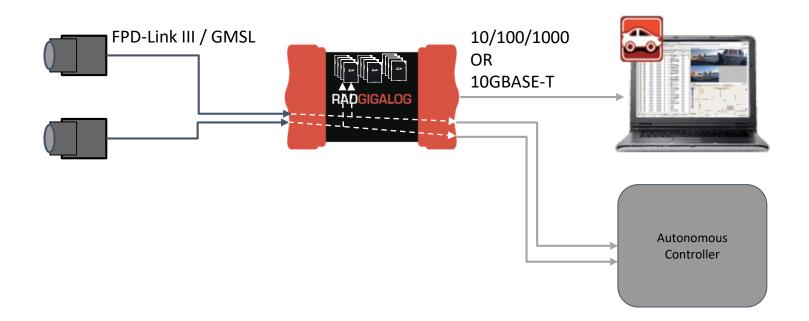


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Camera to Ethernet Conversion

• Log, store and forward uncompressed camera data over Ethernet



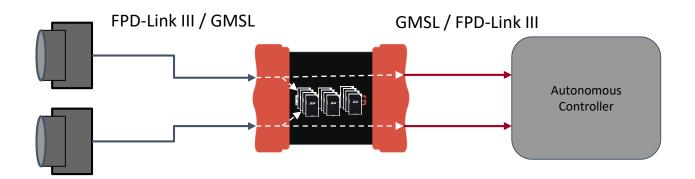


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FPD-Link III / GMSL2 Conversion

• Translate between camera standards GMSL to FPD-LinkIII

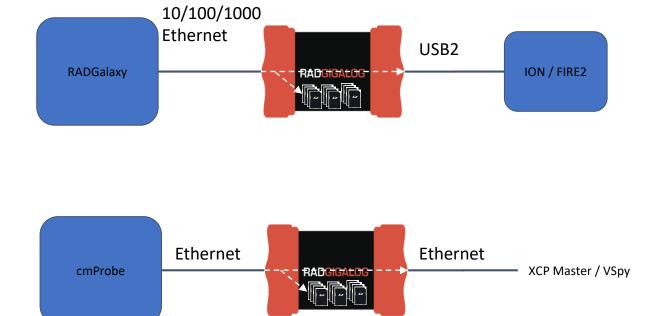




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Storage NAS for Other Devices





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Link Multiple Loggers





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Camera Options

- Powers Camera
- Configures Camera or allows I2C Passthrough
- Can Log I2C Passthrough
- Same SerDes Module as GigaStar



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Questions?

Sales:

icssales@intrepidcs.com +1 (586) 731-7950 x 2

Technical Support:

icssupport@intrepidcs.com www.intrepidcs.com/support +1 (586) 731-7950 x 1





- Those familiar with Automotive Ethernet know that each connection has a "master" and "slave", and this refers to how they link together. But few fully understand the process of PHY linking and what it can mean for you. This presentation will provide a full overview of the linking process.
- <u>http://www.ieee802.org/3/bp/public/mar15/regev</u>
 <u>3bp 01 0315.pdf</u>



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